

A Review Paper on Space Exploration

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Abstract: This paper outlines why space exploration is carried out. There is a summary of method of how missions are selected and their success rate is determined. The kinds of risks associated with Space exploration and what should be done in order to obtain maximum information. The innovation that is being worked upon in order to make human travelling in space more effective and steps being carried out to make space exploration, a field with more possibilities than it is in the recent times.

Keywords: Probabilities, methodology, bio-signature, exploration.

I. INTRODUCTION

The exploration of space is not something that has been carried out after technology took over the world. It has been the subject of curiosity for various individuals since the inception of time. It is a very debatable topic whether there is a need to look out for bodies in space while we are not even able to discover everything on our planet. But the curiosity of human beings never fails to take over the human actions. Also, with the depletion of resources being the most focused environmental issue in the recent times, there may come a time where the resources on earth are completely exhausted and the most influential race of the planet earth may have to look for resources on the extra-terrestrial planets or consider moving to one. For this to be possible, humans are exploring other planets, stars, galaxies. How these milestones, with goal of knowing more about the place outside earth, is reached.

II. MISSION TECHNIQUES

While deciding which space mission to be carried out, the probabilities of success of the mission is determined. This is done by considering four components of the mission that have the maximum influence on the success of the mission. These probabilities are: 1. J and \bar{J} are the propositions that the journey required is, or is not, completed successfully. 2. S and \bar{S} are the propositions that we can successfully, or unsuccessfully, acquire a single sample at the designated sample site. 3. L and \bar{L} are the propositions that the sample does, or does not, contain the target bio signature.

4. T and \bar{T} are the propositions that we have, or do not have, a positive test result for the target bio signature.

2.1 Defining mission outcomes (dependent probabilities)

There are six possible outcomes to the scientific mission and for each outcome we can calculate the probability of it occurring. The mission outcomes can be thought of as dependent probabilities and are listed in Table 1.

Table 1
 Mission outcomes (dependent probabilities) and their definitions.

#	Dependent probabilities	Definition
OP1	$P(\bar{J})$	This is the probability that the journey is not completed successfully. The outcome is that no sample arrives at the point of measurement. When calculating this probability we are allowed to use whatever background knowledge (J) that we have
OP2	$P(\bar{S} J)$	This is the probability that we have a successful journey but do not obtain a sample. Again we can use background knowledge when we calculate this probability
OP3	$P(T, L, S, J)$	This is the probability for our preferred outcome. Namely, a positive test result on a sample that contains the target bio signature, which has happened after a successful journey and sample collection step
OP4	$P(\bar{T}, \bar{L}, S, J)$	This is the probability for an outcome we would prefer to avoid. We successfully acquire a sample containing the target bio signature, but the test returns a negative result following some sort of failure in the physical test or the analysis
OP5	$P(T, \bar{L}, S, J)$	This is the probability for another outcome that we would wish to avoid. We get a positive test result from a sample that does not contain the target bio signature
OP6	$P(\bar{T}, \bar{L}, S, J)$	This is the probability of a negative test result from a sample that does not contain the target bio signature. This outcome is one we would prefer not to experience, but as a true result is better than the outcomes that involve testing errors

Table 2
 Mission steps (independent probabilities) and their definitions.

#	Independent probabilities	Definition
IP1	$P(J)$	This is the probability of successfully completing the necessary journey
IP2	$P(S J)$	This is the probability of successfully obtaining a sample when we assume that the journey is completed successfully; we can also use our background knowledge for this probability
IP3	$P(LS, J, I)$	This is the probability that the sample contains the target bio signature when we assume that the journey is completed successfully and that a sample was successfully obtained
IP4	$P(TL, S, J, I)$	This is the probability that we obtain a true positive result; there is also a related probability of getting false negative result
IP5	$P(\bar{T})=1, S, J, I)$	This is the probability of getting a false positive result; there is also a related probability of getting a true negative result

2.2. Defining mission steps (independent probabilities)

These six dependent probabilities above cover all possibilities and so must sum to one. From this requirement we know that we can have at most five independent pieces of information and the remaining probability is simply the sum of the five independent probabilities subtracted from a total of one. Note that changing the values of $P(J|I)$ or $P(S|J,I)$ will necessarily change all of the other probabilities. So we now introduce five independent probabilities (Table 2).

The dependent and independent probabilities can appear very similar, but are mathematically different. To appreciate the difference one must note the position of the vertical line in the two probabilities. We assume that we have some background

knowledge $I()$, but that T , L , S and J are unknown and we wish to know the probability that T and L , and S and J occur simultaneously.

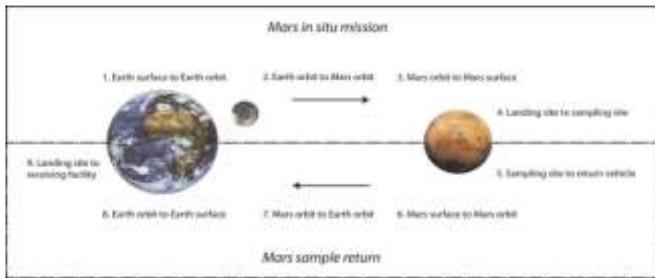
III. JOURNEY PROBABILITY ESTIMATION METHODOLOGIES

Once the mission is into the phase where it has successfully been found capable of being carried out, the primary steps that will be carried out in the mission. In this section we consider how to estimate the independent probabilities for a case involving a single sample, a single sample tool and one target rock type.

The probability that a journey can be completed successfully will depend on where we start, where we want to get to and how we transition between the two. Any journey, e.g. between the points A and B , can be broken down into a series of steps. There will be an intermediate point, e.g. C , and the first step will be $A \rightarrow C$ and the second step will be $C \rightarrow B$. This process can be iterated so that any journey can be broken down into many short steps. The probability of completing a journey is the product of the probability of completing each step. The number of steps that a journey is broken into is a matter of convenience. What is important is the ability to assign a meaningful probability to complete the chosen steps. It is possible that a step, e.g. $C \rightarrow B$, can be completed in two, or more, ways. The particular way chosen will depend on information that is not currently available. What matters at this stage of the analysis is that we can estimate $P(C \rightarrow B)$ using some appropriate methodology. Perhaps the most relevant example of two different journey types is provided by comparing in situ and sample return missions to Mars (Fig. 1). In situ missions rely on analyses on or near the

surface of Mars to achieve their objectives. Sampler return missions select samples on Mars but rely on extensive analyses in Earth laboratories to meet mission goals. To date, only in situ Mars missions have taken place. Substantial planning is taking place for Mars Sample Return and statistical approaches can form part of ongoing preparation activities. In situ and sampler return missions present different engineering challenges. While some features are common to both mission types, sampler return also requires sample storage, departure from Mars, transport to Earth and recovery in a fashion that maintains sample integrity. Mission designs for Mars Sample Return involve the collection and temporary storage (caching) of material on the surface of Mars, before its recovery by a separate mission. If caching is involved, the journey can be complex because a sample must be obtained at one site and then transported to a suitable storage

An example of the steps for a journey to gather samples from the Martian surface may contain: 1. Earth surface to Earth orbit; 2. Earth orbit to Mars orbit; 3. Mars orbit to Mars surface landing site; 4. landing site to sample collection site. For in situ measurements these four steps would constitute the complete journey. For a sampler return mission we would have a lengthy and more complex list of stages to the journey, which might be: 1. Earth surface to Earth orbit; 2. Earth orbit to Mars orbit; 3. Mars orbit to Mars surface landing site; 4. Landing site to sample collection site; 5. Transfer of sample to return vehicle at sample collection site; 6. Sample collection site to Mars orbit; 7. Mars orbit to Earth orbit; 8. Earth orbit to Earth landing site; 9. Earth landing site to sample receiving facility. The probability for the journey element of a sampler return mission will be the probability of the two separate journeys. When estimating if we can obtain a sample at a location with a specific tool there are two issues to consider: does the tool operate as designed, and does the target



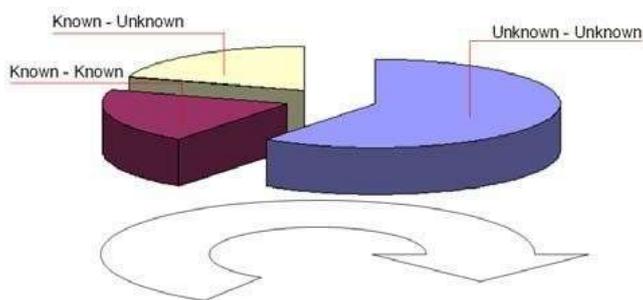
rock exist at the location. Therefore the probability that we can obtain a sample at a specified site is given by

$P(S|I,I) = P(\text{tool works as designed}) \times P(\text{rock type exists at sample location})$ Different tools will have different probabilities of working as designed due to the complexity of their operation. A scoop will be more likely to operate as designed than a rock abrasion tool or corer which in turn is more likely to operate successfully when compared to a more complex drill. The probability that a rock type exists will depend on the ensemble of rock types that might be present. If we assume that the target bio signature is contained in the rock and not in unconsolidated regolith then $P(\text{target rock present}) = [P(\text{rock}) + P(\text{mixture})] / [P(\text{rock}) + P(\text{mixture}) + P(\text{regolith})]$

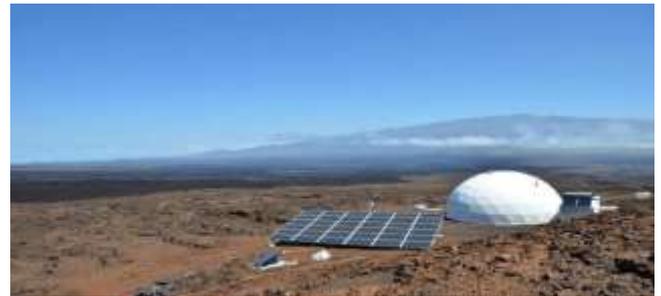
For example, for a location that is judged to have a probability of 1/3 that it is regolith covered, a probability of 1/3 that it is suitable target rock and a probability of 1/3 that it is a mixture, then $P(\text{target rock present}) = 2/3$.

IV. INFORMATION GATHERING

In every mission we can distinguish risk in three possible ways: a) known-known -- we know the risk and have retired it, b) known-unknown -- we know that there is a risk and the risk is modelled and c) unknown-unknown -- we don't even know there is a risk. Exploration is about diving in the unknown-unknown.



Diving into unknown-unknown can be done in two ways, either by actually coming into contact with the unknown identity or through a simulation. Simulation being spoken of, means creating artificial conditions to imitate the real conditions in order to accomplish an objective. Mars being the most discussed future substitute for human habitation, HI-SEAS (Hawaii Space Exploration Analog and Simulation) a NASA funded space simulation, is a series of space simulation studying the effects of isolation and confinement on human beings.



The HI-SEAS habitat

There have been four missions carried out under HI-SEAS, the fourth one being the longest, lasting up to 366 days while the former missions were seven for a period of half a year. The HI-SEAS site has Mars-like geology which allows crews to perform high-fidelity geological field work and add to the realism of the mission simulation as various countries are looking forward to a manned mission to Mars in recent years. There were volunteers living in the habitat, selected from various fields to be able to observe the experience from all possible angles. HI-SEAS offered not only physical isolation and geological similarity. They have developed a robust system of high-latency communication between Crew and Mission Support that imposes a Mars-like 20-minute delay on message reception each way. Communication is solely asynchronous (i.e. no real-time conversations), using email and posts to the mission project site hosted by Basecamp. HI-SEAS offers an environment where communication latency and other mission parameters can

be varied according to study requirements. The habitat consisted of large solar panels for generating power for the entire day, while some power was stored in batteries for the night. The habitat also had a food and water containment which was scarcely supplied to the inhabitants, just like the situation could be when human actually goes to Mars for the initial times. They had to be given psychological and physical training for the mission. They had some restrictions. They couldn't go out of the habitat and breathe air like they were on Earth. They had to wear spacesuits and go outside. The experiences suggested that it is really difficult to walk in that kind of a terrain and wearing the heavy spacesuit made it just harder. The volunteers carried out researches provided by the higher authorities as well as their personal researches.

V. INNOVATION AND IMPROVEMENT

The challenge of space exploration drives a continuing effort to design ever more capable, reliable, and efficient systems requiring the utmost ingenuity. Space exploration missions use the unique capabilities of humans (e.g. on the spot decision-making, cognitive adaptability, versatility) and robots (e.g. precision, sensory accuracy, reliability and expendability) to achieve ambitious exploration goals. Maximizing the productivity of these missions by demanding an effective partnership between humans and machines drives progress in human health care, robotics, automation, and other domains. Space exploration thus supports innovation and economic prosperity by stimulating advances in science and technology, as well as motivating the global scientific and technological workforce, thus enlarging the sphere of human economic activity.



Exoskeleton to help paraplegics walk, derived from space robotic systems

Overcoming the challenges of working in space has led to many technological and scientific advances that have provided

benefits to society on Earth in areas including health and medicine, transportation, public safety, consumer goods, energy and environment, information technology, and industrial productivity.

The wider list of technological benefits encompasses improved solar panels, implantable heart monitors, light-based anti-cancer therapy, cordless tools, light-weight high-temperature alloys used in jet engines, turbines, cameras found in today's cellphones, compact water-purification systems, global search-and-rescue systems and biomedical technologies. Scientific research founded on data from space is also leading to discoveries with benefits for life on Earth. Ongoing research in the space environment of the ISS—in areas such as human physiology, plant biology, materials science, and fundamental physics

— continues to yield insights that benefit society. For example, studies of the human body's response to extended periods in the microgravity environment of the ISS are improving our understanding of the aging process. Fundamental scientific studies of the Martian environment, its evolution and current state represent important benchmarks of terrestrial planetary evolution, and hence, provide a model that some scientists believe will aid our growing understanding of climate change processes on Earth.

Global Technical Workforce Development

Investment in the Apollo Moon exploration program in the 1960s correlates with the level of technical education later attained by students (Figure 3), suggesting that the program's high public profile and dramatic achievements had a widespread influence on the level of US technical education.

A 2009 survey found that fifty percent of the internationally renowned scientists who published in the prestigious journal

Nature during the previous three years had been inspired by Apollo to become scientists; 89 percent of the respondents also agreed that human spaceflight inspires younger generations to study science. One of the lessons from Apollo is that having a visible space exploration program is important in encouraging young people to pursue science, technology, engineering, and mathematics (STEM) fields. Such a program will also send a message to students that they have the possibility of

long-term exciting careers in science and technology.

Today, many space exploration missions include components designed to stimulate young people's interest in STEM. More than 2 million teachers and 43 million students from 49 countries have participated in student experiments and activities associated with the International Space Station (ISS). In some cases, scientists enlisted the help of students to conduct their investigations aboard the ISS, and in other cases students designed space experiments themselves. For example, a program inviting students to design scientific experiments for implementation on the ISS has attracted the interest of tens of thousands of young people.

The early space activities have undoubtedly enlarged our economic sphere, which now extends into space, including the low Earth orbit up to geostationary distances. Recently private initiatives have been launched to extend the economic sphere even further, extending to the Moon, asteroids, and even Mars. This relies on space exploration, which drives the development of new technologies and capabilities (e.g. heavy lift launchers, human and robotic servicing, and autonomous space operations). By developing reliable space exploration systems that incorporate

human decision-making, troubleshooting, and flexibility, possibilities are created for enhancing the economic development of space driven by private sector investments

(e.g. new means to service in-space infrastructure for applications and science purposes can be envisaged). Furthermore, by deepening our understanding of how humans and machines function in space, and developing technologies for space exploration, publicly funded space exploration has lowered the risks and costs associated with accessing and working in space. As a result private investment is increasing in space-based endeavours such

as space transportation systems, Earth-orbiting habitats, space tourism and even planetary mining technologies to eventually harvest precious materials thought to be present in asteroids. Investment in space-based endeavours is becoming sufficiently attractive to private entrepreneurs, so that humankind may be ready to "incorporate the solar system in our economic sphere".

VI. CONCLUSION

With the amount of exposure being given to the students interested in the field and the amount of effort shown by the governments of various countries will be very much crucial in determining the extent of human reach in the space. There are people from all over the world taking space exploration a step forward by

looking at the sky with their telescopes and their scientific thirst for information. The limit of the extent of exploration is totally dependent of the scientific progress of the earth as a whole. However, with the advancements being made in science, more scope of developing new methods of exploration and more innovative methods of travelling in space by improving the suit or the improving the space shuttles just to name a few, the human reach will be increasing with every time period.

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